

## ASYMPTOTIC STABILITY OF SOLUTIONS OF NONLINEAR INTEGRAL EQUATION OF MIXED TYPE

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### Abstract

In this paper, we study the solvability of a nonlinear quadratic integral equation of mixed type. Here we use the technique of measure of noncompactness to prove that this equation has solutions on an unbounded interval. Moreover, the asymptotic behaviour of the solution is also studied.

**Key words:** Measures of noncompactness, Quadratic integral equation of mixed type, Fixed point theorem, Asymptotic stability.

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### 1. Introduction

Measures of noncompactness play very important role in nonlinear analysis. They are often applied to the theories of differential and integral equations as well as to the operator theory and geometry of Banach spaces [2,3]. The concept of a measure of noncompactness was initiated by the fundamental papers of Kuratowski and Darbo. Starting from 1970 there have appeared a lot of papers concerning that concept and its applications [5-11, 16,20].

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Integral equations create a very important and significant part of mathematical analysis and their applications to real world problems [1,4,14,15,17,21]. The theory of integral equations is now well developed with the help of various tools of functional analysis, topology and fixed point theory. Moreover, such integral equations are also applied in the theory of neutron transport as well in the kinetic theory of gases [12, 13, 15, 18, 19]. In this paper, we will investigate the existence and asymptotic behaviour of solutions of a nonlinear quadratic integral equation of mixed type by using the technique of measure of noncompactness and the Darbo fixed point theorem.

## 2. Preliminaries

Let  $(E, \|\cdot\|)$  be an infinite dimensional Banach space with zero element  $0$ . Denote by  $B(x, r)$  the closed ball in  $E$  centered at  $x$  and with radius  $r$ . Let  $B_r$  stand for the ball  $B(0, r)$ . If  $X$  is a subset of  $E$  then  $\bar{X}$ ,  $\text{Conv } X$  denotes the closure and convex closure of  $X$ , respectively. Moreover, the symbol  $M_E$  denotes the family of all nonempty and bounded subsets of  $E$  while  $N_E$  stands for its subfamily consisting of all relatively compact sets.

We will take the following definition of the concept of measure of noncompactness [3].

**Definition 2.1 :** A mapping  $\mu : M_E \rightarrow R_+ = [0, +\infty)$  is said to be a measure of noncompactness in  $E$  if the following conditions are satisfied:

- (i) The family  $\ker \mu = \{X \in M_E : \mu(X) = 0\}$  is nonempty and  $\ker \mu \subset N_E$ ;
- (ii)  $X \subset Y \Rightarrow \mu(X) \leq \mu(Y)$ ;
- (iii)  $\mu(\text{Conv } X) = \mu(X)$ ;
- (iv)  $\mu(\bar{X}) = \mu(X)$ ;
- (v)  $\mu(\lambda X + (1 - \lambda)Y) \leq \lambda\mu(X) + (1 - \lambda)\mu(Y)$  for  $\lambda \in [0, 1]$ ;

(vi) If  $(X_n)$  is a sequence of sets from  $M_E$  such that  $X_{n+1} \subset X_n$ ,  $\bar{X}_n = X_n (n=1,2,3\dots)$

and if  $\lim_{n \rightarrow \infty} \mu(X_n) = 0$ , then the intersection  $X_\infty = \bigcap_{n=1}^{\infty} X_n$  is nonempty.

The family  $\ker \mu$  described in (i) is called the kernel of the measure of noncompactness  $\mu$ .

A measure  $\mu$  is said to be sublinear if it satisfies the following two conditions:

(vii)  $\mu(\lambda X) = |\lambda| \mu(X)$  for  $\lambda \in R$ ;

(viii)  $\mu(X + Y) \leq \mu(X) + \mu(Y)$ .

Moreover, a measure  $\mu$  satisfying the condition

(ix)  $\mu(X \cup Y) = \max\{\mu(X), \mu(Y)\}$  will be referred to as a measure with maximum property.

Other facts concerning measures of noncompactness and their properties may be found [3]. For our purpose we will need the following fixed point theorem due to Darbo.

**Theorem 2.1:** [3]. Let  $Q$  be nonempty bounded closed convex subset of the space  $E$  and let  $G : Q \rightarrow Q$  be a continuous operator such that  $\mu(GX) \leq k\mu(X)$  for any nonempty subset  $X$  of  $Q$  where  $k$  is a constant,  $k \in [0, 1)$ . Then  $G$  has a fixed point in the set  $Q$ .

**Remark 2.1 :** Under the assumptions of the above theorem it can be shown that the set  $\text{Fix } G$  of fixed points of  $G$  belonging to  $Q$  is a member of the family  $\ker \mu$ .

This observation allows us to characterize solutions of the equation investigated.

In the sequel we will work in the Banach space  $BC(R_+)$  consisting of all real functions defined, bounded and continuous on  $R_+$ . The space  $BC(R_+)$  is equipped with the standard norm  $\|x\| = \sup\{|x(t)| : t \geq 0\}$ .

Fix a nonempty bounded subset  $X$  of  $BC(R_+)$  and a positive number  $T > 0$ . For  $x \in X$  and  $\varepsilon \geq 0$  let us denote by  $\omega^T(x, \varepsilon)$  the modulus of continuity of the function

$x$  on the interval  $[0, T]$ , i.e.,  $\omega^T(x, \varepsilon) = \sup\{|x(t) - x(s)| : t, s \in [0, T], |t - s| \leq \varepsilon\}$

Further, let us put

$$\omega^T(X, \varepsilon) = \sup\{\omega^T(x, \varepsilon) : x \in X\}$$

$$\omega_0^T = \lim_{\varepsilon \rightarrow 0} \omega^T(x, \varepsilon), \quad \omega_0(X) = \lim_{T \rightarrow 0} \omega_0^T(X)$$

For a fixed number  $t \geq 0$  we denote

$$X(t) = \{x(t) : x \in X\}$$

and

$$\text{diam } X(t) = \sup\{|x(t) - y(t)| : x, y \in X\}.$$

Finally, let us define the function  $\mu$  on the family  $M_{BC(R_+)}$  by the formula

$$\mu(X) = \omega_0(X) + \lim_{t \rightarrow \infty} \sup \text{diam } X(t).$$

It can be shown [3] that the function  $\mu$  is a sublinear measure of noncompactness with the maximum property in the space  $BC(R_+)$ . The kernel of this measure contains nonempty and bounded sets  $X$  such that functions from  $X$  are locally equicontinuous on  $R_+$  and the thickness of the bundle formed by functions from  $X$  tends to zero at infinity. This property of the kernel  $\ker \mu$  allows us to characterize (in terms of asymptotic behavior) solutions of the following integral equation and will be used in the rest of the paper.

### 3. Main Result

Consider the following nonlinear functional-integral equation of mixed type

$$x(t) = f(t, x(t)) + F\left(t, x(t), \int_0^t g(t, s, x(s)) ds, \int_0^a h(t, s, x(s)) ds\right), \quad t \geq 0 \quad \dots (1)$$

We will assume that the functions involved in (1) satisfy the following conditions

(H1)  $f: R_+ \times R \rightarrow R$  is a continuous function  $f(t, 0) \in BC(R_+)$ ;

(H2) There exists a continuous function  $m(t) : R_+ \rightarrow R_+$  such that  $|f(t, x) - f(t, y)| \leq m(t)|x - y|$  for all  $x, y \in R, t \in R_+$ ;

(H3)  $F: R_+ \times R \times R \times R \rightarrow R$  is a continuous function  $F(t, 0, 0, 0) \in BC(R_+)$ ;

(H4) There exists continuous functions  $n_1(t), n_2(t), n_3(t) : R_+ \rightarrow R_+$  such that  $|F(t, x_1, y_1, z_1) - F(t, x_2, y_2, z_2)| \leq n_1(t)|x_1 - x_2| + n_2(t)|y_1 - y_2| + n_3(t)|z_1 - z_2|$  for  $x_i, y_i, z_i \in R, i = 1$  to  $2, t \in R_+$ ;

(H5)  $g : R_+ \times R_+ \times R \rightarrow R$  is a continuous function such that

$$\lim_{t \rightarrow \infty} n_2(t) \int_0^t |g(t, s, x(s))| ds = 0 \text{ uniformly with respect to } x \in BC(R_+);$$

(H6)  $h : R_+ \times R_+ \times R \rightarrow R$  is a continuous function and there exists continuous functions  $p, q, u, v : R_+ \rightarrow R_+$  such that

$$|h(t, s, x) - h(t, s, y)| \leq p(t)q(s)|x - y|,$$

$$|h(t, s, 0)| \leq u(t)v(s),$$

$$\lim_{t \rightarrow \infty} n_3(t)u(t) = 0$$

for all  $t \in R_+, x \in R$ ;

Take

$$Q = \int_0^a q(s) ds,$$

$$V = \int_0^a v(s) ds,$$

(H7) Let

$$k = \sup_{t \in R_+} \{m(t) + n_1(t) + n_3(t) p(t) Q\} \text{ be such } 0 \leq k < 1.$$

**Remark 3.1:** The concept of the asymptotic stability of a solution is understood in the following sense [5,6].

For any  $\varepsilon > 0$  there exist  $T > 0$  and  $r > 0$  such that if  $x, y \in B_r$  and  $x = x(t)$ ,  $y = y(t)$  are solutions of (1) then  $|x(t) - y(t)| \leq \varepsilon$  for  $t \geq T$ .

**Theorem 3.1:** Suppose the hypotheses (H1) - (H7) hold. Then (1) has at least one solution  $x(t)$  which belongs to the space  $BC(R_+)$  and is asymptotically stable on the interval  $R_+$ .

**Proof:**

Consider the operator  $P$  defined on the space  $BC(R_+)$  by the formula

$$(Px)(t) = f(t, x(t)) + F(t, x(t), \int_0^t g(t, s, x(s)) ds, \int_0^a h(t, s, x(s)) ds), \quad t \geq 0,$$

From the assumptions it is clear that, the function  $P_x$  is continuous on the interval  $R_+$  for any function  $x \in BC(R_+)$ .

From our assumptions, we get:

$$\begin{aligned} |(Px)(t)| &\leq |f(t, x(t))| + |F(t, x(t), \int_0^t g(t, s, x(s)) ds, \int_0^a h(t, s, x(s)) ds)| \\ &\leq |f(t, x(t)) - f(t, 0)| + |F(t, x(t), \int_0^t g(t, s, x(s)) ds, \int_0^a h(t, s, x(s)) ds) \\ &\quad - F(t, 0, 0, 0)| + |f(t, 0)| + |F(t, 0, 0, 0)| \end{aligned}$$

$$\begin{aligned}
&\leq \left[ m(t) + n_1(t) \right] x(t) + n_2(t) \int_0^t |g(t, s, x(s))| ds \\
&\quad + n_3(t) \int_0^a |h(t, s, x(s))| ds + |f(t, 0)| + |F(t, 0, 0, 0)| \\
&\leq \left[ m(t) + n_1(t) \right] x(t) + n_2(t) \int_0^t |g(t, s, x(s))| ds \\
&\quad + n_3(t) \int_0^a |h(t, s, x(s)) - h(t, s, 0)| ds + n_3(t) \int_0^a |h(t, s, 0)| ds \\
&\quad + |f(t, 0)| + |F(t, 0, 0, 0)| \\
&\leq \left[ m(t) + n_1(t) \right] x(t) + n_2(t) \int_0^t |g(t, s, x(s))| ds \\
&\quad + n_3(t) p(t) \int_0^a q(s) |x(s)| ds + n_3(t) u(t) \int_0^a v(s) ds \\
&\quad + |f(t, 0)| + |F(t, 0, 0, 0)|
\end{aligned}$$

The above estimate allows us to infer that the function  $Px$  is bounded on the interval  $R_+$ . Thus  $Px \in BC(R_+)$ .

Moreover, we obtain

$$\|Px\| \leq k \|x\| + A \quad \dots (2)$$

where

$$A = \sup \left\{ n_2(t) \int_0^t |g(t, s, x(s))| ds + n_3(t) u(t) V + |f(t, 0)| + |F(t, 0, 0, 0)| : t \geq 0 \right\}.$$

Obviously  $A < \infty$  by virtue of the assumptions (H1), (H3), (H5) and (H6). Since  $k < 1$ , from (2), the operator  $P$  transforms  $B_r$  into itself for  $r = A/(1-k)$ .

Next we show that  $P$  is continuous on the ball  $B_r$ . For this let us fix  $\varepsilon > 0$  and take  $x, y \in B_r$  such that  $\|x - y\| \leq \varepsilon$ . Then for arbitrarily fixed  $t \in R_+$ , we get

$$\begin{aligned} |(Px)(t) - (Py)(t)| &\leq |f(t, x(t)) - f(t, y(t))| \\ &+ \left| F(t, x(t), \int_0^t g(t, s, x(s)) ds, \int_0^a h(t, s, x(s)) ds) \right. \\ &\left. - F(t, y(t), \int_0^t g(t, s, y(s)) ds, \int_0^a h(t, s, y(s)) ds) \right| \quad \dots (3) \end{aligned}$$

$$\begin{aligned} &\leq [m(t) + n_1(t)] |x(t) - y(t)| \\ &+ n_2(t) \int_0^t |g(t, s, x(s)) - g(t, s, y(s))| ds \\ &+ n_3(t) \int_0^a |h(t, s, x(s)) - h(t, s, y(s))| ds \\ &\leq [m(t) + n_1(t)] |x(t) - y(t)| \\ &+ n_2(t) \int_0^t |g(t, s, x(s)) - g(t, s, y(s))| ds \\ &+ n_3(t) p(t) \int_0^a |q(s)| |x - y| ds \quad \dots (4) \end{aligned}$$

Now denote by  $T$  a real positive number such that

$$+ n_2(t) \int_0^t |g(t, s, x(s))| ds \leq (1-k)\varepsilon/2 \quad \dots (5)$$

for  $t \geq T$ .

Consider two cases:

( $\alpha$ )  $t \geq T$ . Then from (4) and (5), we obtain

$$(Px)(t) - (Py)(t) \leq k\varepsilon + (1-k)\varepsilon/2 + (1-k)\varepsilon/2 = \varepsilon$$

( $\beta$ )  $t < T$ . Then let  $\omega = \omega(\varepsilon)$  be the function defined by the formula

$$\omega(\varepsilon) = \sup\{|g(t, s, x) - g(t, s, y)| : t, s \in [0, T], x, y \in [-r, r], |x - y| \leq \varepsilon\}.$$

Taking into account that the function  $g = g(t, s, x)$  is uniformly continuous on the set  $[0, T] \times [0, T] \times [-r, r]$ , we deduce that  $\omega(\varepsilon) \rightarrow 0$  as  $\varepsilon \rightarrow 0$ .

Thus virtue of (4), we get

$$(Px)(t) - (Py)(t) \leq k\varepsilon + \sup\{n_2(t) : t \in [0, T]\} T\omega(\varepsilon)$$

Now, linking cases ( $\alpha$ ) and ( $\beta$ ), we can deduce the operator  $P$  is continuous on the ball  $B_r$ .

Take a nonempty set  $X \subset B_r$ . Then, for  $x, y \in X$ , and for a fixed  $t \geq 0$ , calculating in the same way as in the proof of estimate (3), we obtain

$$\begin{aligned} |(Px)(t) - (Py)(t)| &\leq [m(t) + n_1(t)] |x(t) - y(t)| \\ &\quad + n_2(t) \int_0^t |g(t, s, x(s)) - g(t, s, y(s))| ds \\ &\quad + n_3(t) p(t) \int_0^a q(s) |x - y| ds \end{aligned}$$

Hence we can easily deduce,

$$\text{diam}(PX)(t) \leq k \text{diam} X(t)$$

$$+ \sup_{x, y \in X} \{n_2(t) [\int_0^t |g(t, s, x(s))| ds + \int_0^t |g(t, s, y(s))| ds]\}$$

Now by our assumptions, we get

$$\limsup_{t \rightarrow \infty} \text{diam} (PX)(t) \leq k \limsup_{t \rightarrow \infty} \text{diam} X(t). \quad \dots (6)$$

Further, fix arbitrarily  $T > 0$  and  $\varepsilon > 0$ . Choose a function  $x \in X$  and take  $t, s \in [0, T]$  such that  $|t - s| \leq \varepsilon$ . Without loss of generality, we may assume that  $s < t$ . Then

$$\begin{aligned} |(Px)(t) - (Px)(s)| &\leq |f(t, x(t)) - f(s, x(s))| \\ &+ \left| F(t, x(t), \int_0^t g(t, \tau, x(\tau)) d\tau, \int_0^a h(t, \tau, x(\tau)) d\tau) \right. \\ &\quad \left. - F(s, x(s), \int_0^s g(s, \tau, x(\tau)) d\tau, \int_0^a h(s, \tau, x(\tau)) d\tau) \right| \\ &\leq |f(t, x(t)) - f(t, x(s))| + |f(t, x(s)) - f(s, x(s))| \\ &+ \left| F(t, x(t), \int_0^t g(t, \tau, x(\tau)) d\tau, \int_0^a h(t, \tau, x(\tau)) d\tau) \right. \\ &\quad \left. - F(t, x(s), \int_0^s g(s, \tau, x(\tau)) d\tau, \int_0^a h(s, \tau, x(\tau)) d\tau) \right| \\ &+ \left| F(t, x(s), \int_0^s g(s, \tau, x(\tau)) d\tau, \int_0^a h(s, \tau, x(\tau)) d\tau) \right. \\ &\quad \left. - F(s, x(s), \int_0^s g(s, \tau, x(\tau)) d\tau, \int_0^a h(s, \tau, x(\tau)) d\tau) \right| \end{aligned}$$

$$\begin{aligned}
& \leq [m(t) + n_1(t)] |x(t) - x(s) + f(t, x(s)) - f(s, x(s))| \\
& \quad + n_2(t) \left| \int_0^t g(t, \tau, x(\tau)) d\tau - \int_0^s g(s, \tau, x(\tau)) d\tau \right| \\
& \quad + n_3(t) \int_0^a |h(t, \tau, x(\tau)) - h(s, \tau, x(\tau))| d\tau \\
& \quad + \left| F(t, x(s), \int_0^s g(s, \tau, x(\tau)) d\tau, \int_0^a h(s, \tau, x(\tau)) d\tau) \right. \\
& \quad \left. - F(s, x(s), \int_0^s g(s, \tau, x(\tau)) d\tau, \int_0^a h(s, \tau, x(\tau)) d\tau) \right| \\
& \leq [m(t) + n_1(t) + n_3(t)p(t)Q] |x(t) - x(s)| \\
& \quad + |f(t, x(s)) - f(s, x(s))| + n_2(t) \int_s^t |g(t, \tau, x(\tau))| d\tau \\
& \quad + n_2(t) \int_0^s |g(t, \tau, x(t)) - g(s, \tau, x(\tau))| d\tau \\
& \quad + n_3(t) \int_0^a |h(t, \tau, x(t)) - h(s, \tau, x(\tau))| d\tau \\
& \quad + \left| F(t, x(s), \int_0^s g(s, \tau, x(\tau)) d\tau, \int_0^a h(s, \tau, x(\tau)) d\tau) \right. \\
& \quad \left. - F(s, x(s), \int_0^s g(s, \tau, x(\tau)) d\tau, \int_0^a h(s, \tau, x(\tau)) d\tau) \right|
\end{aligned}$$

Taking supremum, we get

$$\begin{aligned} \omega^T(Px, \varepsilon) \leq & k\omega^T(x, \varepsilon) + \omega_r^T(f, \varepsilon) + \varepsilon n_2(t) \sup\{|g(t, \tau, x(\tau))| : t, \tau \in [0, T], |x| \leq r\} \\ & + T n_2(t) \omega_r^T(g, \varepsilon) + a n_3(t) \omega_r^T(h, \varepsilon) + \omega_r^T(F, \varepsilon) \end{aligned}$$

where

$$\omega_r^T(g, \varepsilon) = \sup\{|g(t, \tau, x) - g(s, \tau, x)| : t, s, \tau \in [0, T], |t - s| \leq \varepsilon, |x| \leq r\}$$

$$\omega_r^T(h, \varepsilon) = \sup\{|h(t, \tau, x) - h(s, \tau, x)| : t, s, \tau \in [0, T], |t - s| \leq \varepsilon, |x| \leq r\}$$

$$\begin{aligned} \omega_r^T(F, \varepsilon) = \sup\{|F(t, x, y, z) - F(s, x, y, z)| : t, s, \tau \in [0, T], |t - s| \leq \varepsilon, \\ |x| \leq r, |y| \leq M, |z| \leq N\} \end{aligned}$$

$$M = \sup\left\{\int_0^s |g(s, \tau, x(\tau))| d\tau : s, \tau \in [0, T], |x| \leq r\right\}$$

$$N = \sup\left\{\int_0^a |h(s, \tau, x(\tau))| d\tau : s, \tau \in [0, T], |x| \leq r\right\}$$

Applying the assumptions, we infer easily that the functions  $g = g(t, \tau, x)$  and  $h = h(t, \tau, x)$  are uniformly continuous on the set  $[0, T] \times [0, T] \times [-r, r]$ , while the functions  $f = f(t, x)$  and  $F = F(t, x, y, z)$  are uniformly continuous on  $[0, T] \times [-r, r]$  and  $[0, T] \times [-r, r] \times [-M, M] \times [-N, N]$  respectively.

Hence we deduce that  $\omega_r^T(g, \varepsilon) \rightarrow 0, \omega_r^T(h, \varepsilon) \rightarrow 0, \omega_r^T(f, \varepsilon) \rightarrow 0$  and  $\omega_r^T(F, \varepsilon) \rightarrow 0$  as  $\varepsilon \rightarrow 0$ .

Now, from the above estimate, we get

$$\omega_0^T(PX) \leq k\omega_0^T(X)$$

and, further

$$\omega_0(PX) \leq k\omega_0(X) \quad \dots (7)$$

Now, linking (6) and (7), we arrive at the following inequality:

$$\mu(PX) \leq k\mu(X) \quad \dots (8)$$

The above inequality in conjunction with Theorem. 2.1 allows us to deduce that there exists a solution  $x = x(t)$  of (1) in the space  $BC(R_+)$ . Moreover, in view of (3) and the definition of asymptotic stability, we infer that  $x(t)$  is asymptotically stable on the interval  $R_+$ .

**Remark 3.2:** Observe that the information about the asymptotic stability of the solution  $x = x(t)$  of (1) can also be deduced from the fact that the set of all solutions of (1) belongs to  $\ker \mu$ . Keeping in mind the description of the kernel of the measure of noncompactness  $\mu$ , we obtain that every solution  $x = x(t)$  of (1) is asymptotically stable.

#### 4. Example

Consider the following functional-integral equation:

$$\begin{aligned} x(t) = & \frac{t}{1+t^2} x(t) + \frac{1}{4} \ln(1+|x(t)|) + \sin t \int_0^t \frac{1}{4+t^3} \exp(-s-x^2(s)) ds \\ & + \cos(t|x(t)|) \int_0^1 \frac{\exp(-t-s)}{1+|x(s)|} ds, t \in R_+ \quad \dots (9) \end{aligned}$$

The above equation takes the form of (1) with  $g(t,s,x(s)) = \frac{1}{4+t^3} \exp(-s-x^2(s))$ ,

$$h(t,s,x(s)) = \frac{\exp(-t-s)}{1+|x(s)|}, f(t,x) = \frac{t}{1+t^2} x(t) \text{ and } a = 1$$

Let us observe that

$$\begin{aligned} |f(t,x) - f(t,y)| & \leq \frac{t}{1+t^2} |x-y|, \\ |F(t,x_1,y_1,z_1) - F(t,x_2,y_2,z_2)| & \leq \frac{1}{4} |x_1-x_2| + t|y_1-y_2| + |z_1-z_2| \end{aligned}$$

Now, it is easily seen that the assumptions (H2) and (H4) are satisfied

$$m(t) = \frac{t}{1+t^2}, n_1(t) = \frac{1}{4}, n_2(t) = t, n_3(t) = 1.$$

Also, we have

$$|g(t, s, x(s))| \leq \frac{1}{4+t^3},$$

$$|h(t, s, 0)| \leq \exp(-t-s),$$

$$|h(t, s, x) - h(t, s, y)| \leq \exp(-t-s) |x - y|.$$

It is clear that (9) satisfies assumptions (H5), (H6) and (H7)  $p(t) = u(t) = \exp(-t)$  and  $q(s) = v(s) = \exp(-s)$ .

Taking into account the above established facts and applying Theorem 3.1, we infer that (9) has at least one solution  $x(t)$  which belongs to the space  $B_{\infty}$  and is asymptotically stable on the interval  $R_+$ .

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