

## FAULT-TOLERANT METRIC BASES FOR SQUARE OF PATHS

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### Abstract

A pair of vertices  $u$  and  $v$  in a graph  $G$  is said to be resolved by the vertex  $w$  if the distance between  $u$  and  $w$  is not equal to the distance between  $v$  and  $w$  symbolically we write  $d(u, w) \neq d(v, w)$ . For a simple connected graph  $G$ , a set of vertices  $R$  of  $G$  is said to be a resolving set of  $G$  if every pair of vertices of  $G$  are resolved by some vertices in  $R$ , i.e., every pair of vertices of  $G$  are uniquely identified by some vertex elements in  $R$ . The resolving set of  $G$  containing the minimum number of vertices is the metric basis and the minimum cardinality of the metric basis is called the metric dimension of  $G$ . A resolving set  $F$  for the graph  $G$  is said to be fault tolerant if for each  $u \in F$ ,  $F \setminus \{u\}$  is also a resolving set for  $G$  and the minimum cardinality of the fault-tolerant resolving set is the fault-tolerant metric dimension. In this article, we study the fault-tolerant metric dimension for  $P_n^2$  for all  $n \geq 5$ . We have successfully deduced the fault-tolerant metric dimension of  $P_n^2$  for all  $n \geq 5$ . The existence of at least  $n$  fault-tolerant metric bases for the same graph has been ascertained in this paper.

**Keywords:** Fault-tolerant resolving set, resolving set, metric basis.

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## 1. Introduction

Every network can be represented by some graph. The identification of every vertex (node) uniquely is of great prominence so as to maintain the security of the network. Now the question that needs to be posed is "What should be an identifying method for a given graph?". The distances in graphs play a vital role for the identification of vertices uniquely when the graph is connected. Let  $G = (V(G), E(G))$  be a simple connected graph and  $R = \{r_1, r_2, \dots, r_m\}$  be a set of vertices with respect to  $R$ , we define the codes for each vertex of  $G$  as follows

$$code_R(v) = (d(r_1, v), d(r_2, v), \dots, d(r_m, v)),$$

where  $d(u, v)$  denotes the distance between the vertices  $u$  and  $v$  in  $G$ . It is to be noted that the code of the vertex  $v$  with respect to  $R \subset V(G)$  is a vector with  $|R|$  components. A natural intuition can be established that  $R$  can identify all vertices uniquely if  $code_R(v) \neq code_R(w)$  for every pair of vertices  $v$  and  $w$ . Such type of set  $R$  is called a resolving set. Consequently, a set of vertices  $R$  of  $G$  is said to be a resolving set if  $code_R(v) \neq code_R(w)$  every pair of vertices  $v$  and  $w$ . The metric basis for a graph  $G$  is the resolving set of  $G$  containing the minimum number of vertices. The minimum cardinality  $\beta(G)$  of the resolving set  $R$  is called the *metric dimension* of  $G$  and denoted is by  $\beta(G)$ . A fault-tolerant resolving set with minimum cardinality is called *fault-tolerant metric basis* for  $G$ . The concept of metric dimensions was first instigated by Slater [1], Harry and Melter [2]. The metric basis  $\beta(G)$  is the minimum cardinality of the resolving set. Elements in the basis were considered as sensors in an application given in [2]. The problem of finding the metric dimension for a general graph is a NP-hard. Khuller et al. [3] gave a construction that proves that the metric dimension of a graph is NP-hard.

Although the applications of metric bases arise in many various platforms such as Robot Navigation, Network Optimization, Sensor networks, heavily used by government organization of India such as DRDO, ISRO etc., but still they have some reservations due to the fact that if some detectors (elements of metric basis) are faulty, then it is not possible to identify the nodes uniquely. In order to improve the accuracy of the detection or the robustness of the system Hernando et al. introduced concept of fault-tolerant metric dimension in [7]. This concept is defined as follows: A resolving set  $F$  of a graph  $G$  is fault-tolerant if  $F \setminus \{v\}$  is also a resolving set, for every vertex  $v \in F$ . The *fault-tolerant metric dimension* of  $G$ , denoted by  $\beta'(G)$ , is the minimum cardinality of a fault-tolerant resolving set. A fault-tolerant resolving set of order  $\beta'(G)$  is called a fault-tolerant metric basis. The problem of determining the fault-tolerant metric dimension is a NP hard problem and results are known only for some classes of graphs. Hernando et al. [7] characterized all fault tolerant resolving sets for any tree  $T$ . In this article they also have shown the relation  $\beta'(G) \leq \beta(G)(1 + 2 \cdot 5^{\beta(G)-1})$  for every graph  $G$ . For a cycle  $C_n$ , the fault-tolerant metric dimension has been determined by Javaid et al. in [11] as  $\beta'(C_n) = 3$ . Basak et al. [12] determine the fault-tolerant metric dimension of  $C_n^3$ . In this paper, we study the fault-tolerant

## Fault-Tolerant Metric Bases for Square of Paths

metric dimension of  $P_n^2$ . We firstly found out the lower bound for  $\beta'(P_n^2)$  and then determine fault tolerant metric bases. Lastly, we were able to determine the exact value for the same.

The rest of the paper are organized as follows: In the Preliminaries section, we explicitly define and explain the various different terminologies and expressions with the help of which we establish the various results for the fault-tolerant metric dimension of  $P_n^2$ . In section named as Fault-tolerant metric dimension of  $P_n^2$ , we have put forward and proved the different lemmas, theorems and examples to claim our results. In this section we were able to find that the lower bound for the fault-tolerant metric dimension of  $P_n^2$  for  $n \geq 5$  i.e.,  $\beta'(P_n^2) \geq 4$ . We have also successfully established that there exists a fault-tolerant resolving set of  $P_n^2$  with cardinality 4 for  $n \geq 5$ , which later led to the findings of the upper bound for the fault-tolerant metric dimension of  $P_n^2$  which was found as 4 i.e.,  $\beta'(P_n^2) \leq 4$ . The later part of the article consists of the concluding remark, acknowledgement and the references that we have used to construct the article.

### 2. Preliminaries

Let  $G = (V(G), E(G))$  be a graph with vertex set  $V(G)$  and edge set  $E(G)$ . Two vertices  $u$  and  $v$  are called *adjacent* if there is an edge between  $u$  and  $v$ . An edge  $e$  is called *adjacent to a vertex  $v$*  if  $e$  has one end as  $v$ . The degree of a vertex  $v \in V(G)$  is the number of edges adjacent to  $v$ . The distance between two vertices  $u$  and  $v$ , denoted by  $d_G(u, v)$  (or simply  $d(u, v)$ ), is the length of shortest paths between them. A path graph  $P_n$  (simply we call path) is an  $n$ -vertex graph in which every vertex has degree 2 except two end vertices. Henceforth we denote the vertex set  $V(P_n)$  by  $\{v_0, v_1, \dots, v_{n-1}\}$  and hence degree of  $v_\ell$  is 2 for all  $\ell \in \{1, 2, \dots, n-2\}$ , whereas both the vertices  $v_0$  and  $v_{n-1}$  has degree one. The square of a connected graph  $G$ , denoted by  $G^2$ , is the graph on the same vertex set as  $G$  and two vertices  $u$  and  $v$  are adjacent in  $G^2$  if  $d_G(u, v) \leq 2$ . Therefore, vertex set  $V(P_n^2)$  is  $\{v_0, v_1, \dots, v_{n-1}\}$  and the following proposition is true for  $P_n^2$ .

**Proposition 2.1** *The distance between two vertices  $v_i$  and  $v_j$  in  $P_n^2$  is given by  $d(v_i, v_j) = \left\lceil \frac{|i-j|}{2} \right\rceil$  and the diameter of  $P_n^2$  is  $\left\lceil \frac{n-1}{2} \right\rceil$ .*

Now we define two sets which forms a partition of the vertex set of  $P_n^2$ .

**Definition 2.1** A vertex  $v_i$  in  $P_n^2$  is called an *even or odd vertex* if accordingly, the subscript  $i$  being an even or odd integer. Let  $S_{[0]}$  and  $S_{[1]}$ , respectively, denote set of all even and odd vertices of  $P_n^2$ . Note that  $V(P_n^2) = S_{[0]} \cup S_{[1]}$  is a partition of  $V(P_n^2)$ . For  $t \in \{0, 1\}$ , an element  $v_j \in V(P_n^2)$  is called the *largest element* of  $S_{[t]}$  if  $j$  is the largest integer such that  $v_j \in S_{[t]}$ . By intuition similarly we will define the term

second largest element in the set  $S_{[t]}$  for  $t \in \{0, 1\}$ . The following lemma gives a basic property of a fault-tolerant resolving set for an arbitrary graph.

**Lemma 2.1**[11] *A set  $F \subset V(G)$  is a fault-tolerant resolving set of  $G$  if and only if every pair of vertices in  $G$  is resolved by at least two vertices of  $F$ .*

### 3. Fault-tolerant metric dimension of $P_n^2$

In this section, we determine the fault-tolerant metric dimension of  $P_n^2$ . First we give a lower bound for  $\beta'(P_n^2)$  and then determine fault tolerant metric bases. We need following results to determine a lower bound for  $\beta'(P_n^2)$ .

**Lemma 3.1** *Let  $v_j$  resolves two consecutive vertices  $v_a$  and  $v_{a+1}$ . Then*

- (a)  $j \equiv a \pmod{2}$  with  $j \leq a$
- (b)  $j \equiv a + 1 \pmod{2}$  with  $j \geq a + 1$ .

**Proof:**

- (a) Let  $v_j \in V(P_n^2)$  with  $j \leq a$ . Then the distances of two vertices  $v_a$  and  $v_{a+1}$  from  $v_j$  are  $\left\lfloor \frac{a-j}{2} \right\rfloor$  and  $\left\lfloor \frac{a-j+1}{2} \right\rfloor$ , respectively. Let  $a - j = 2q + r$  where  $0 \leq r \leq 1$ . Then  $\left\lfloor \frac{a-j}{2} \right\rfloor \neq \left\lfloor \frac{a-j+1}{2} \right\rfloor$  implies  $\left\lfloor \frac{2q+r}{2} \right\rfloor \neq \left\lfloor \frac{2q+r+1}{2} \right\rfloor$  and this is true only when  $r = 0$ . Therefore  $j \equiv a \pmod{2}$  with  $j \leq a$ .
- (b) Let  $v_j \in V(P_n^2)$  with  $j \geq a + 1$ , i.e.,  $v_j$  be a right-side vertex of  $v_{a+1}$ . Then the distances of two vertices  $v_a$  and  $v_{a+1}$  from  $v_j$  are  $\left\lfloor \frac{j-a}{2} \right\rfloor$  and  $\left\lfloor \frac{j-a-1}{2} \right\rfloor$ , respectively. Let  $j - a - 1 = 2q + r$  where  $0 \leq r \leq 1$ . Then  $\left\lfloor \frac{j-a}{2} \right\rfloor \neq \left\lfloor \frac{j-a-1}{2} \right\rfloor$  implies  $\left\lfloor \frac{2q+r+1}{2} \right\rfloor \neq \left\lfloor \frac{2q+r}{2} \right\rfloor$  and this is true only when  $r = 0$ . Therefore  $j \equiv a + 1 \pmod{2}$  with  $j \geq a + 1$ .

**Lemma 3.2** *If  $F$  misses an element from  $\{v_1, v_2, \dots, v_{n-2}\}$ , then  $|F| \geq 4$ .*

**Proof:** Let  $v_i \notin F$  for some  $i \in \{1, 2, \dots, n - 2\}$ . Then consider three consecutive vertices  $u_{i-1}$ ,  $u_i$ ,  $u_{i+1}$ . For each  $\ell \in \{i, i + 1\}$ , let  $R_\ell$  denotes the set of vertices which resolves  $u_{\ell-1}$  and  $u_\ell$ . Then from Lemma 3.1,  $R_i = \{j \equiv i - 1 \pmod{2} : 0 \leq j \leq i - 1\} \cup \{j \equiv i \pmod{2} : i \leq j \leq n - 1\}$  and  $R_{i+1} = \{j \equiv i \pmod{2} : 0 \leq j \leq i\} \cup \{j \equiv i + 1 \pmod{2} : i + 1 \leq j \leq n - 1\}$ . Since  $F$  be a fault-tolerant resolving set,  $|F \cap R_i| \geq 2$  and  $|F \cap R_{i+1}| \geq 2$ . It is clear that  $R_i \cap R_{i+1} = \{u_i\}$ . Since  $v_i \notin F$ ,  $|F \cap (R_i \setminus \{v_i\})| \geq 2$  and  $|F \cap (R_{i+1} \setminus \{v_i\})| \geq 2$ . Since  $(R_i \cap R_{i+1}) \setminus \{v_i\} = \emptyset$ ,  $|F| \geq |F \cap (R_i \setminus \{v_i\})| + |F \cap (R_{i+1} \setminus \{v_i\})| \geq 4$ .

**Theorem 1** For a square of path  $P_n^2$  with  $n \geq 5$ ,  $\beta'(P_n^2) \geq 4$ .

*Proof:* Let  $F$  be an arbitrary fault-tolerant resolving set of  $P_n^2$ . If  $F$  miss a vertex  $v_i$  for some  $i \in \{1, 2, \dots, n-2\}$ , then applying Lemma 3.2, we have  $|F| \geq 4$ . Again if  $F$  does not miss any vertex from  $\{v_1, v_2, \dots, v_{n-2}\}$ , then  $|F| \geq n-2$ . Therefore,  $|F| \geq \min\{4, n-2\}$  and hence the result is true as  $F$  being an arbitrary fault-tolerant resolving set of  $P_n^2$ .

**Theorem 2** For every integer  $n \geq 5$ , there exists a fault-tolerant resolving set of  $P_n^2$  with cardinality 4.

**Proof:** For the existence of a fault-tolerant resolving set having cardinality 4, we need to construct a set  $F$  for which every pair of vertices of  $P_n^2$  must be resolved by at least two elements of  $F$ . The first four consecutive vertices or the last consecutive vertices do have this property. Let us consider  $F = \{v_0, v_1, v_2, v_3\}$ , i.e.,  $F$  be the set of first four consecutive vertices. We show that  $F$  is a fault-tolerant resolving set. Let  $u$  and  $v$  be arbitrary two vertices in  $V(P_n^2)$ . Without loss of generality, we may assume  $u$  is a left side vertex of  $v$ . Then there exist  $i$  and  $j$  with  $i < j$  such that  $u = v_i$  and  $v = v_j$ . If both of  $u$  and  $v$  are in  $F$ , then the pair of vertices  $u$  and  $v$  are resolved by both of them. So, in this case proof is trivial. We take the following two remaining cases.

**Case 1: Exactly one of  $u$  and  $v$  is in  $F$ .** Since  $u = v_i$  and  $v = v_j$  with  $i < j$ , so in this case  $v$  cannot be in  $F$ ; otherwise,  $u$  will also be in  $F$  as  $F$  contains consecutive vertices starting from initial vertex  $v_0$ . Since  $u \in F$ , the pair of vertices  $u$  and  $v$  is resolved by a vertex  $u$ . Now we have to find another vertex  $w \in F$  that will resolve the vertices  $u$  and  $v$ . In the below we give the distances of  $u$  and  $v$  from the both vertices  $v_0$  and  $v_1$ .

$$\begin{aligned} d(v_0, u) &= d(v_0, v_i) = \left\lfloor \frac{i}{2} \right\rfloor \\ d(v_1, u) &= d(v_1, v_i) = \left\lfloor \frac{i-1}{2} \right\rfloor \\ d(v_0, v) &= d(v_0, v_j) = \left\lfloor \frac{j}{2} \right\rfloor \\ d(v_1, v) &= d(v_1, v_j) = \left\lfloor \frac{j-1}{2} \right\rfloor. \end{aligned}$$

Since  $u = v_i \in F$ ,  $0 \leq i \leq 3$  and then the above equations give  $d(v_\ell, u) \leq 2$  and  $d(v_\ell, v) \geq 3$  provided  $j \geq 6$ . Thus, the pair  $u = v_i$  and  $v = v_j$  are resolved by two vertices  $v_0$  and  $v_1$  which are elements of  $F$ , provided  $j \geq 6$ . Now we take  $j \leq 6$ . Since  $v = v_j \notin F \setminus \{v_0, v_1, v_2, v_3\}$ ,  $j \in \{4, 5\}$ . Now for  $j \in \{4, 5\}$ , i.e.,  $v_j \in \{v_4, v_5\}$ , we calculate a  $4 \times 6$  matrix  $D_F$  in which  $(i+1)$ -th column represents the code of the vertex  $v_i$  with respect to  $F$ , where  $0 \leq i \leq 5$ .

$$D_F = \begin{pmatrix} 0 & 1 & 1 & 2 & 2 & 3 \\ 1 & 0 & 1 & 1 & 2 & 2 \\ 1 & 1 & 0 & 1 & 1 & 2 \\ 2 & 1 & 1 & 0 & 1 & 1 \end{pmatrix}$$

From the above matrix it is clear that every pair of columns has at least two distinct corresponding entries and hence  $u = v_i$  and  $v = v_j$  are resolved by at least two elements of  $F$ , when  $v_i \in F$  and  $v_j \in \{v_4, v_5\}$ .

**Case 2: Both  $u$  and  $v$  are not in  $F$ .** Recall that  $u = v_i$  and  $v = v_j$ , where  $i < j$ . Let  $i \equiv a \pmod{2}$ , where  $a \in \{0, 1\}$ . Then both  $v_a$  and  $v_{a+2}$  are in  $F$ . Since  $v_\ell \in F = \{v_0, v_1, v_2, v_3\}$  and both  $v_i$  and  $v_j$  are outside of  $F$ ,  $\ell < i < j$ . We show that  $d(v_\ell, v_i) \neq d(v_\ell, v_j)$  for each  $\ell \in \{a, a+2\}$ . Note that  $\ell \equiv a \pmod{2}$ . Here below, we calculate the distances of  $v_i$  and  $v_j$  from  $v_\ell$  for each  $\ell \in \{a, a+2\}$ .

$$\begin{aligned} d(v_\ell, v_i) &= \left\lceil \frac{i - \ell}{2} \right\rceil = \frac{i - \ell}{2} \\ d(v_\ell, v_j) &= \left\lceil \frac{j - \ell}{2} \right\rceil \\ &= \left\lceil \frac{i - \ell + j - i}{2} \right\rceil \\ &\geq \frac{i - \ell}{2} + 1 \text{ (as } i - \ell \equiv 0 \pmod{2}) \\ &= d(v_\ell, v_i) + 1 \end{aligned}$$

Therefore, we have  $d(v_\ell, v_i) \neq d(v_\ell, v_j)$  for each  $\ell \in \{a, a+2\}$ . Hence if  $i$  is even, then the pair of vertices  $u = v_i$  and  $v = v_j$  are resolved by the both  $v_0$  and  $v_2$  whereas for odd  $i$ , the pair  $v_i$  and  $v_j$  are resolved by two elements  $v_1$  and  $v_3$ .

On account of Case 1 and Case-2, finally we have that every pair of vertices of  $P_n^2$  are resolved by at least two elements of  $F = \{v_0, v_1, v_2, v_3\}$  and this thus grants the existence of a fault-tolerant resolving set for  $P_n^2$  with cardinality 4.

**Remark 3.1** From above theorem we may conclude that  $\beta'(P_n^2) \leq 4$  for  $n \geq 5$ .

**Remark 3.2** Renaming the vertices of  $P_n^2$  by  $w_i = v_{n-1-i}$ , one can show that  $F = \{w_0, w_1, w_2, w_3\}$  (the set of last four consecutive vertices of  $P_n^2$ ) forms a fault-tolerant resolving set for  $P_n^2$  for  $n \geq 5$ .

**Remark 3.3** By similar argument as used in the proof of Theorem 2, one can show that any four consecutive vertices form a fault-tolerant resolving set for  $P_n^2$  for  $n \geq 5$ .

**Theorem 3.** For any integer  $n \geq 5$ ,  $\beta'(P_n^2) = 4$ .

## Fault-Tolerant Metric Bases for Square of Paths

**Proof:** If  $n \geq 6$ , then from Theorem 1 and Remark 3.1, we have  $\beta'(P_n^2) = 4$ . Therefore the theorem is true for  $n \geq 6$ . Now we take  $n = 5$ . Then from Theorem 1,  $\beta'(P_5^2) \geq 3$  and the equality occurs only if  $F = \{v_1, v_2, v_3\}$  from a fault-tolerant resolving set of  $P_n^2$ . We show that  $F$  does not form a fault-tolerant resolving set for  $P_n^2$ . We consider a  $3 \times 5$  matrix  $D_F$  in which  $(i + 1)$ -th column represents the code of  $v_i$  with respect to  $F$  for each  $i \in \{0, 1, 2, 3, 4\}$ .

$$D_F = \begin{pmatrix} 1 & 0 & 1 & 1 & 2 \\ 1 & 1 & 0 & 1 & 1 \\ 2 & 1 & 1 & 0 & 1 \end{pmatrix}$$

In the above matrix, we see that the entries in 1st and 5th columns differ by only one place and hence  $F = \{v_0, v_1, v_2\}$  cannot be a fault-tolerant resolving set of  $P_5^2$ . Therefore,  $\beta'(P_5^2) = 4$ .

The proof is complete.

**Example 3.1** Here we calculate the codes of each vertex for  $P_{10}^2$  with respect to the fault-tolerant resolving set  $F = \{v_0, v_1, v_2, v_3\}$ .

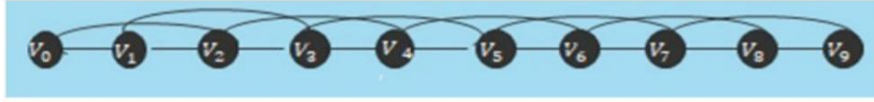


Figure 1: The graph  $P_{10}^2$ .

The distance matrix  $D$  for  $P_{10}^2$  is given by

$$D = \begin{matrix} & \begin{matrix} v_0 & v_1 & v_2 & v_3 & v_4 & v_5 & v_6 & v_7 & v_8 & v_9 \end{matrix} \\ \begin{matrix} v_0 \\ v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \\ v_6 \\ v_7 \\ v_8 \\ v_9 \end{matrix} & \begin{pmatrix} 0 & 1 & 1 & 2 & 2 & 3 & 3 & 4 & 4 & 5 \\ 1 & 0 & 1 & 1 & 2 & 2 & 3 & 3 & 4 & 4 \\ 1 & 1 & 0 & 1 & 1 & 2 & 2 & 3 & 3 & 4 \\ 2 & 1 & 1 & 0 & 1 & 1 & 2 & 2 & 3 & 3 \\ 2 & 2 & 1 & 1 & 0 & 1 & 1 & 2 & 2 & 3 \\ 3 & 2 & 2 & 1 & 1 & 0 & 1 & 1 & 2 & 2 \\ 3 & 3 & 2 & 2 & 1 & 1 & 0 & 1 & 1 & 2 \\ 4 & 3 & 3 & 2 & 2 & 1 & 1 & 0 & 1 & 1 \\ 4 & 4 & 3 & 3 & 2 & 2 & 1 & 1 & 0 & 1 \\ 6 & 4 & 4 & 3 & 3 & 2 & 2 & 1 & 1 & 0 \end{pmatrix} \end{matrix}$$

In the matrix  $D$ , the  $(i, j)$ -th entry represents the distance between  $v_i$  and  $v_j$ . Now if we choose a  $4 \times 10$  sub-matrix  $D_F$  consisting of first four rows, we have the

following matrix whose  $(j + 1)$ -th column represents the code of  $v_j$  with respect to the set  $F = \{v_0, v_1, v_2, v_3\}$ .

$$D_F = \begin{matrix} & c(v_0) & c(v_1) & c(v_2) & c(v_3) & c(v_4) & c(v_5) & c(v_6) & c(v_7) & c(v_8) & c(v_9) \\ \begin{matrix} v_0 \\ v_1 \\ v_2 \\ v_3 \end{matrix} & \begin{pmatrix} 0 & 1 & 1 & 2 & 2 & 3 & 3 & 4 & 4 & 5 \\ 1 & 0 & 1 & 1 & 2 & 2 & 3 & 3 & 4 & 4 \\ 1 & 1 & 0 & 1 & 1 & 2 & 2 & 3 & 3 & 4 \\ 2 & 1 & 1 & 0 & 1 & 1 & 2 & 2 & 3 & 3 \end{pmatrix} \end{matrix}$$

In the above matrix  $D_F$ , every pair of columns is different at two places and hence  $F$  is a fault-tolerant resolving set. For example, if we take 6-th and 7-th column, then these two columns are differed in 2nd and 4-th places. Again, if we choose a  $3 \times 10$  sub-matrix consisting of first three rows, we have the following matrix whose  $(j + 1)$ -th column represents the code of  $v_j$  with respect to the set  $F' = \{v_0, v_1, v_2\}$ .

$$D_{F'} = \begin{matrix} & c(v_0) & c(v_1) & c(v_2) & c(v_3) & c(v_4) & c(v_5) & c(v_6) & c(v_7) & c(v_8) & c(v_9) \\ \begin{matrix} v_0 \\ v_1 \\ v_2 \end{matrix} & \begin{pmatrix} 0 & 1 & 1 & 2 & 2 & 3 & 3 & 4 & 4 & 5 \\ 1 & 0 & 1 & 1 & 2 & 2 & 3 & 3 & 4 & 4 \\ 1 & 1 & 0 & 1 & 1 & 2 & 2 & 3 & 3 & 4 \end{pmatrix} \end{matrix}$$

Here the 6-th and 7-th column are different at only one place. So,  $F'$  cannot be fault-tolerant resolving set for  $P_n^2$ .

#### 4. Concluding Remark

In this article we have determined the fault-tolerant metric dimension for  $P_n^2$  for all  $n \geq 5$ . We also have shown the existence of at least  $n$  fault-tolerant metric bases for the same graph. The readers may try to find all fault-tolerant metric bases for  $r$ -th power of paths or in particular, for square of paths. This article gives a solution to the problem of placement of optimal numbers of sensors in a network when it is structured as square of paths. By giving more than one fault-tolerant metric bases for  $P_n^2$ , we present an alternative placement of sensors in the network when one solution is not suitable for an organization who are planning to place the sensors. If a sensor fails which can be catastrophic the fault-tolerant system is able to use reversion to fallback to a safer mode. The advantages of using such a system are that it reduces redundancy, there is no slowdown of the given system and no assumptions are made for the distribution of fault.

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